

Swing Clamps with Sturdy Swing Mechanism Top flange type, with optional position monitoring,

double acting, max. operating pressure 120 bar



Hydraulic swing clamps are used for clamping of workpieces, when it is essential to keep the clamping area free of straps and clamping components for unrestricted workpiece load-

This series obtains very high clamping forces already at 120 bar and can directly be connected to the low-pressure hydraulics of the machine tool. An additional power unit for power

With the sturdy swing mechanism and the optional position monitoring these swing clamps

Automatic manufacturing systems with very

· Clamping fixtures with workpiece loading by

• Test systems for motors, gears and axes

workholding is no longer necessary.

are particularly suitable for:

short cycle times

handling systemsTransfer lines

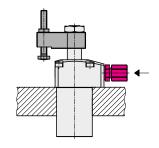
• Special machine tools

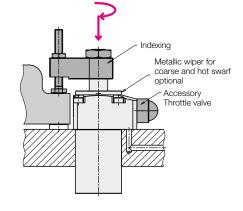
Assembly lines

Advantages

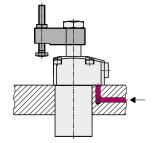
- 4 sizes available
- Compact design partially recessible
- Very high clamping force already at 120 bar
- Sturdy swing mechanism
- Very short clamping time
- Insensitive against high flow rates
- Indexing of the clamping arm in a specified position is possible
- Special swing angle easily realisable
- FKM wiper standard
- Metallic wiper optional
- Throttle valves available as accessory
- Position monitoring available as accessory
- Mounting position: any

Installation and connecting possibilities Pipe thread

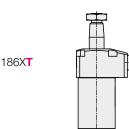




Drilled channels

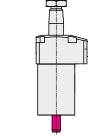


Versions Without switch rod



With switch rod

186XQ



Description

Application

ing and unloading.

The hydraulic swing clamp is a pull-type cylinder where a part of the total stroke is used to swing the piston.

Due to the sturdy swing mechanism the angle position of the clamping arm remains the same after a slight collision with the workpiece during loading and unloading or during clamping.

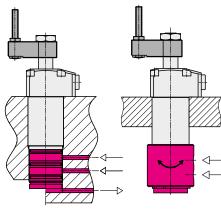
The angle position of the clamping arm is fixed with a dowel pin.

The FKM wiper at the piston rod can be protected against coarse and hot swarf by an optionally available metallic wiper (see page 6). The version with extended switch rod is provided for mounting of pneumatic or electrical position monitorings (accessory).

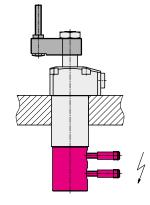
Important notes see page 6.

Accessories

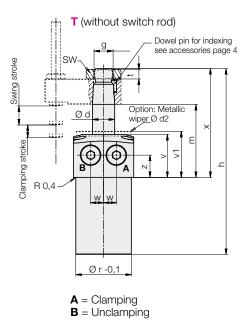
Pneumatic position monitoring



Electrical position monitoring



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Clamping position ±1° Swing direction Swing direction cw CCW p3 (4X) Swing angle 90° off-position ±3° P2 (4, Ξ Indexing mark represented in clamping position , pt 04 S G max.

Swing angle

1. Swing angle 90° and 0° (standard)

	Part no.
90° cw	186X X <mark>090 R</mark> XX
90° ccw	186X X <mark>090 L</mark> XX
0°	186X X000 0XX

2. Swing angle α < 90°

 α = 15° to 75° in gradation of 5°

By insertion of a distance plate, the return stroke of the piston is reduced and thus the Hydraulic symbol swing angle is reduced.

Clamping stroke and clamping position remain the same. The swing stroke and the dimensions h, m and x are reduced by y:

 $y = (90^\circ - \alpha^\circ) \star k$ (k see chart page 3)

Dimension 8 \pm 0.5 is lengthened by the value y.

Part no.	1866 T <mark>045 L</mark> 27
Desired swing angle	45° ccw
Swing clamp	1866T090L27
Example:	

Shortening:

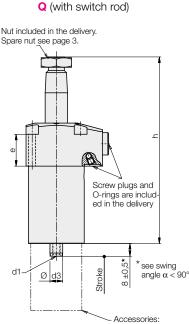
 $y = (90^{\circ} - 45^{\circ}) * 0.125 \text{ mm/}^{\circ} = 5.625 \text{ mm}$

3. Swing angle > 90°

Available on request!

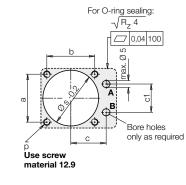
Important notes see page 6.

Operating conditions, tolerances and other data see data sheet A 0.100.



Position monitoring

Connecting scheme



Accessory Throttle valve

Throttle valves are used

- to reduce the swing speed of the clamping arm:
- to improve the synchronism of several swing clamps.

This application is only possible for manifoldmounting connection through drilled channels.

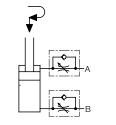
B ma>

SW1 SW2 SW3

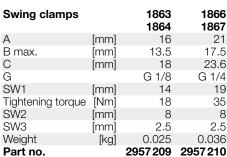
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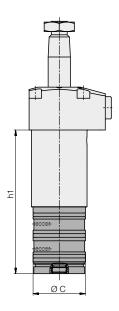
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8



Part no.

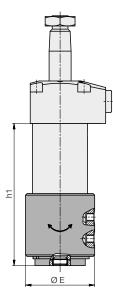




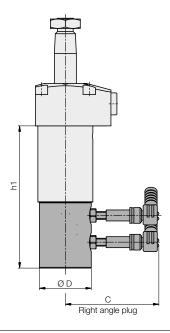
Accessories

Pneumatic position monitoring (page 5) Cartridge type

Pipe thread connection



Electrical position monitoring (page 6)



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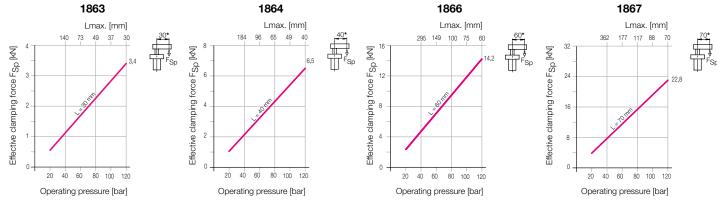
Technical data

Max. pulling force	. ,	[kN]	4.04	7.65	17	27.6
Effective clamping	force	[kN]		-	on of the clamping force	
Clamping stroke		[mm]	8	8	10	10
Swing stroke		[mm]	8	13	17	19
Total stroke		[mm]	16	21	27	29
Min. operating pre	essure	[bar]	20	20	20	20
Max. flow rate	clamping	[cm³/s]	13.5	33.5	96	167
	unclamping	[cm ³ /s]	20	53.5	145	255
Piston area	clamping	[cm ²]	3.36	6.37	14.16	23
	unclamping	[cm ²]	4.9	10.17	21.23	33.18
Oil volume / stroke	9	[cm ³]	5.4	13.4	38.3	66.7
Oil volume / return	n stroke	[cm ³]	7.9	21.4	57.4	102
Piston Ø		[mm]	25	36	52	65
a		[mm]	30.5	40	56	68
b		[mm]	30.5	40	56	68
C		[mm]	22.5	28	36	42
c1		[mm]	18	24	36	45
Ød		[mm]	14	22	30	36
Ød1		[mm]	M5 x 14.5 deep	M6 x 11.5 deep	M6 x 16.0 deep	M6 x 16.0 deep
Ø d2		[mm]	34.5	44.5	52.5	58.5
Ø d3 f7		[mm]	8	10	12	12
		[mm]	20	19.5	12	23.5
e SW			20 SW 19	SW 27	SW 36	23.3 SW 46
		[mm]	M12	M18 x 1.5	M24 x 1.5	M30 x 1.5
g		[mm]				
G		[]	G 1/8	G 1/8	G 1/4	G 1/4
h		[mm]	117	149	178.5	203.5
h1		[mm]	90.5	110	132	141
k		[mm/°]	0.056	0.095	0.125	0.125
L		[mm]	38	50	70	86
L1		[mm]	48	60	82	96
m		[mm]	46	54	64.5	72.5
n		[mm]	19	25	35	43
р		[mm]	M4 (10.9)	M5 (10.9)	M8 (10.9)	M10 (10.9)
Øp1		[mm]	4.3	5.5	9	11
p2		[mm]	4	5	7	9
рЗ		[mm]	3	3	6	7
Ø r -0.1		[mm]	35	47	63	78
Øs-0.2		[mm]	36	48	64	79
t		[mm]	6	9	10	12
V		[mm]	27	29.5	34.5	39
v1		[mm]	29	31.5	36.5	41
W		[mm]	8.1	11	15	19
х		[mm]	68.5	88	101.5	119.5
Z		[mm]	14	13.5	15.5	15.5
Weight, approx.		[kg]	0.7	1.5	3.0	5.0
	Clockwise rotation 90°		1863 X090 R16M	1864 X090 R21M	1866 X090 R27M	1867 X090 R29M
5	Swing direction 90° ccw		1863 X090 L16M	1864 X090 L21 M	1866 X090 L27 M	1867 X090 L29M
) degree		1863 X000 016M	1864 X000 021 M	1866 X000 027 M	1867 X000 029M
Spare O-ring	-	[mm]	7 x 1.5	7 x 1.5	8 x 1.5	8 x 1.5
Part no.			3000 342	3000 342	3000 343	3000 343
i ui t no.						
Spare nut DIN 936	3		M12	M18 x 1.5	M24 x 1.5	M30 x 1.5
	3	[Nm]	M12 12 3302115	M18 x 1.5 30	M24 x 1.5 62	M30 x 1.5 110

Code letter X see page 2.

M = Option metallic wiper (see also page 6)

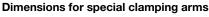
Effective clamping force with accessory clamping arm as a function of the oil pressure

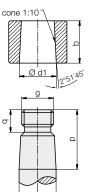


* Clamping force for other lengths see page 4.

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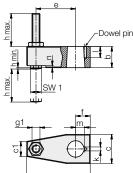
Accessories - Clamping arms • Metallic wipers Calculation of the flow rate • Calculation of the clamping force



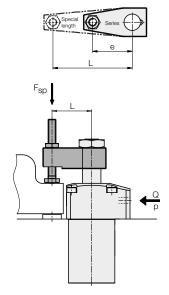


Ød

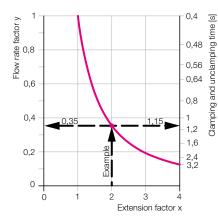
Clamping arm



Special clamping arm



Adm. flow rate and clamping time as a function 1. of the clamping arm extension



Swing clamps		1863	1864	1866	1867
а	[mm]	48	65	96	114
b	[mm]	16	25	27	35
С	[mm]	22	34	52	60
c1	[mm]	12	19	31	36
Ød	[mm]	14	22	30	36
Ø d1 -0.05	[mm]	14	22	30	36
е	[mm]	30	40	60	70
f	[mm]	11	17	25	30
g	[mm]	M12	M18 x 1.5	M24 x 1.5	M30 x 1.5
g1	[mm]	M6	M8	M12	M16
h min.	[mm]	1	1	1	1
h max.	[mm]	40	46	54	63
Ø k +0.1	[mm]	3	3	6	6
I +0.5	[mm]	8.5	8.5	12.5	12.5
m ±0.05	[mm]	6.6	10.3	15	18.1
n	[mm]	1.5	2.5	6	8
р	[mm]	22.5	34	37	47
q	[mm]	8.5	11.5	12.5	15.5
SW 1	[mm]	8	10	18	24
Moment of inertia of Je	[kgmm ²]	44	230	1284	3247
Part no.					
Clamping arm with con and dowel pin	tact bolt	0354243	0354 249	0354254	0354256
Dowel pin		3 m 6x8 3301 854	3 m 6x8 3301 854	6 m 6x12 3300 325	6 m 6x12 3300 325
Metallic wiper		0341227	0341 228	0341 229	0341230

Admissible flow rate

With the accessory clamping arm and the admissible flow rate as per chart (page 3) the shortest clamping time is approx. 0.4 seconds. Longer special clamping arms have a higher torque of inertia. To avoid an overload of the swing mechanism, the flow rate has to be reduced:

$$Q_{L} = Q_{e} * \sqrt{\frac{J_{e}}{J_{L}}} cm^{3}/s$$

Q = Flow rate as per chart (page 3)

 \vec{Q}_{L}^{e} = Flow rate with special clamping arm \vec{J}_{L} = Torque of inertia accessory clamping arm Je

= Torque of inertia special clamping arm J,

If the torques of inertia are not known, the admissible flow rate can be determined according to the following example:

Conditions: The special clamping arm is longer, has however the form (cross section) of the accessory clamping arm, as shown on the left.

Example: Swing clamp 1863T090R16

L = 60 mm

e = 30 mm as per above chart $Q_a = 13.5 \text{ cm}^3/\text{s}$ (as per chart page 3)

Extension factor
$$x = \frac{L}{e} = \frac{60 \text{ mm}}{30 \text{ mm}}$$

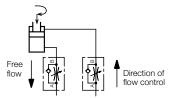
2. Flow rate factor
as per diagram
$$\rightarrow$$
 y = 0.35

3. Max. flow rate

$$Q_L = y * Q_e = 0.35 * 13.5 \text{ cm}^3/\text{s} = 4.7 \text{ cm}^3/\text{s}$$

as per diagram → approx. 1.15 s

Throttling of the flow rate



Calculation of the clamping force

The diagrams on page 3 show the effective clamping force with accessory clamping arm (L = e).

With longer clamping arms (L > e) the degree of efficiency is reduced. This is considered in the following calculation.

The constants (A....E) for the 4 sizes are shown in the chart.

Constant	1863	1864	1866	1867
А	29.68	15.68	7.06	4.35
В	0.177	0.069	0.023	0.013
С	102.9	260.5	853.8	1596
D	3053	4087	6026	6939
E	18.2	17.86	19.55	20.86

Effective clamping force

$$\mathsf{F}_{_{\mathrm{Sp}}} = \frac{\mathsf{p}}{\mathsf{A} + (\mathsf{B} \star \mathsf{L})} \leq \mathsf{F}_{_{adm.}} \qquad [kN]$$

Admissible clamping force*)

$$F_{adm} = \frac{C}{L}$$
 [kN]

Admissible operating pressure

$$p_{adm} = \frac{D}{L} + E \le 120$$
 [bar]

p = pressure [bar]

- = 2 L = special length [mm]

> *) With a desired clamping arm length L the clamping force must not exceed the admissible value.

Example: Swing clamp 1863 T090 R16 Special clamping arm L = 60 mm

1. Admissible clamping force

$$F_{adm} = \frac{C}{L} = \frac{102.9}{60} = 1.71 \text{ kN}$$
2. Admissible operating pressure

$$p_{adm} = \frac{D}{L} + E = \frac{3053}{60} + 18.2 = 69 \text{ bar} < 120$$

4

Accessories Pneumatic position monitoring • Mounting body

Application

The pneumatic position monitoring signals the following conditions by closing two bore holes:

- 1. Piston extended and clamping arm in offposition.
- 2. Piston in clamping area and clamping arm in clamping position.

For each control function, a pneumatic line has to be provided at the clamping fixture.

Description

The cartridge type of the pneumatic position monitoring can be easily retrofitted at all swing clamps with switch rod (186XQ0XX). When moving to a switching position, the air pressure in the supply line increases and operates a differential pressure switch or an electro-pneumatic pressure switch.

Pneumatic port

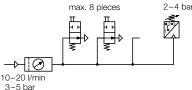
Cartridge type

The swing clamp with the mounted position monitoring and inserted O-rings is put into the location hole and immediately ready for use.

Mounting body

The mounting body is put onto the cartridge-type version and held by the supplied safety ring. The pneumatic ports M5 can be rotated by 360°.

Monitoring by pneumatic pressure switch



For the evaluation of the pneumatic pressure increase, standard pneumatic pressure switches can be used. With one pressure switch up to 8 position monitorings can be controlled (see circuit diagram).

It has to be considered that process-safe functioning of pneumatic controls is only guaranteed with throttled air pressure and air flow rate.

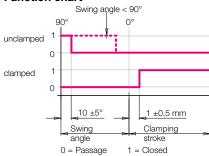
Technical data

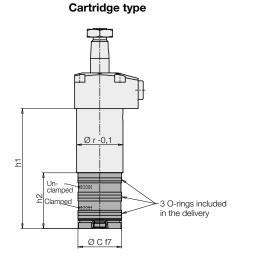
Connection	Drilled channels or threads M5
Nominal diameter	2 mm
Max. air pressure	10 bar
Range of operating pressure	35 bar
Differential pressure*) at	
3 bar system pressure	min. 1.5 bar
5 bar system pressure	min. 3.5 bar
Air volume **)	1020 l/min
*) Minimum progouro difforono	if one or soveral

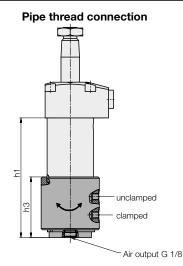
*) Minimum pressure difference, if one or several position monitorings are not operated.

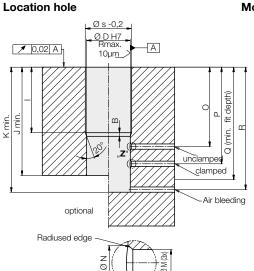
**) For measuring of the flow rate appropriate devices are available.

Function chart

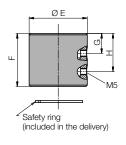








Mounting body



Detail "Z"

Swing clamps		1863Q0XX	1864Q0XX	1866Q0XX	1867Q0XX				
ØA	[mm]	35	47	63	78				
В	[mm]	2.5-0.5	2.5-05	2.5-0.5	2.5-0.5				
ØCf7	[mm]	33	42	45	45				
Ø D H7	[mm]	33	42	45	45				
ØE	[mm]	44	53	56	56				
F	[mm]	40	47	48.8	50.8				
G	[mm]	14.95	16.35	13.4	14.05				
Н	[mm]	28.75	33.35	35.4	36.75				
h1	[mm]	90.5	110	132	141				
h2	[mm]	42	49	55	57				
h3	[mm]	46	53	54.8	56.8				
	[mm]	49.5	62	78	85				
J min.	[mm]	83	101.5	123.5	132.5				
K min.	[mm]	94.5	114	136	145				
ØM	[mm]	4	4	4	4				
ØN	[mm]	5	5	5	5				
0	[mm]	60	73.5	89.5	96.5				
Р	[mm]	73	90.5	111.5	118.5				
Q min.	[mm]	85	103	125	134				
R	[mm]	92.5	112	134	143				
Ør-0.1	[mm]	35	47	63	78				
Øs-0.2	[mm]	36	48	64	79				
Part no. Cartridge type Swing angle									
0° or 90°		0353918	0353924	0353928	0353941				
15° to 75° = XX *)		03539180 <mark>XX</mark>	03539240 <mark>XX</mark>	03539280 <mark>XX</mark>	03539410XX				
Part no. Mounting	body for re	trofitting of the 0353950	cartridge type 0353951	0353952	0353953				
*) in gradation of 5°) in gradation of 5° (see page 2, "swing angle $lpha < 90^{\circ}$ ")								

Actual issue see www.roemheld-group.com

Application

The electrical position monitoring signals the following conditions due to damping of two inductive proximity switches:

 Piston extended, clamping arm in off-position.

2. Piston in clamping area, clamping arm in clamping position.

For each control function, an electrical line has to be provided at the clamping fixture.

Description

The electrical position monitoring can be easily retrofitted at all swing clamps with switch rod (186XQOXX).

- Included in our delivery are:
- 1 Signal sleeve with screw
- 1 Adapter with 4 countersunk screws
- 1 Control housing with 3 set screws
- 2 Inductive proximity switches with right angle plug (if ordered)

The signal sleeve is screwed onto the switch rod.

The adapter is mounted with 4 countersunk screws at the bottom cover.

The control housing can be put onto the adapter in any angular position and locked with 3 set screws.

For information on adjustment of proximity switches, see operating manual.

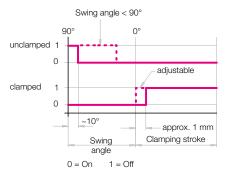
Important notes

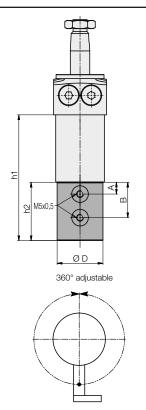
Inductive position monitorings are not suitable for the use in coolant and swarf areas. According to the corresponding application conditions, safety measures have to be planned and checked later on.

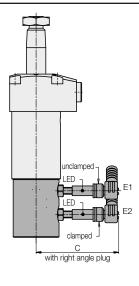
Technical data

Operating voltage	1030 V DC
Max. residual ripple	10%
Max. constant current	100 mA
Switching function	interlock
Output	PNP
Housing material	stainless steel
Thread	M 5 x 0.5
Code class	IP 67
Ambient temperature	-25+70°C
LED function display	yes
Protected against short circuits	yes
Type of connection	plug
Length of cable	5 m

Function chart







Possible position of the proximity switches

Swing clamps		1863Q0XX	1864Q0XX	1866Q0XX	1867Q0XX
А	[mm]	8.5	8.5	8.5	8.5
В	[mm]	25.5	30.5	37.5	39.5
C approx.	[mm]	59.5	61	62	62
ØD	[mm]	33	42	45	45
h1	[mm]	90.5	110	132	141
h2	[mm]	42	49	55	57
Part no. Swing a	ingle 0° or 90)°			
with switch and plu	Jg	0353920	0353926	0353930	0353943
without switch and	without switch and plug		0353927	0353931	0353944
Part no. 15° to	75° = XX*)				
with switch and plu	Jg	0353 920 0 <mark>XX</mark>	03539260XX	0353 930 0 <mark>XX</mark>	03539430 <mark>XX</mark>
without switch and plug		03539230XX	03539270XX	03539310XX	0353 944 0 <mark>XX</mark>
Part no. Spare par	ts				
Inductive proximity	switch	3829 198	3829 198	3829198	3829198
Right angle plug 5 m		3829 099	3829099	3829099	3829099
Part no. Spare parts Inductive proximity switch		0353 920 0353 923 0353 920 0XX 0353 923 0XX 3829 198	0353927 03539260XX 03539270XX 3829198	0353931 03539300XX 03539310XX 3829198	0353 94 0353 943 0X 0353 944 0X 3829 19

*) in gradation of 5° (see page 2, "swing angle $\alpha < 90^{\circ}$ ")

Important notes

Swing clamps must only be used for clamping of workpieces in industrial applications and may only be operated with hydraulic oil. They can generate very high forces. The workpiece, the fixture or the machine must be in the position to compensate these forces.

In the effective area of piston rod and clamping arm there is the danger of crushing.

The manufacturer of the fixture or the machine is obliged to provide effective protection devices. The swing clamp has no overload protection device. When mounting the clamping arm, the clamping arm or the hexagon socket in the piston have to be backed up for tightening or untightening the fixing nut.

During loading and unloading of the fixture and during clamping a collision with the clamping arm has to be avoided.

Remedy: Mount position adaptor.

Wiper system

The standard FKM wiper has a high chemical resistance against most cooling and cutting fluids.

The optional metallic wiper protects the FKM wiper against mechanical damage due to big or hot swarf.

It consists of a radially floating wiping disk and a retaining disk.

The metallic wiper can be delivered already mounted ("M") or as an accessory for retrofitting (see page 4).

Attention!

The metallic wiper is not suitable for dry machining or minimum quantity lubrication. Also in applications with very little grinding swarf, the standard FKM wiper has a better protection effect.

If there is any danger that small particles stick to the piston rod, the metallic wiper disk can also be replaced by a hard plastic disk.

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