

# Linear Actuators RA 60 K

Max. lifting force 300 to 600 N, stroke from 100 to 200 mm version with limit switches or stroke measuring system



# **Advantages**

- Compact design
- Outstanding durability
- Variable mounting position
- Maintenance free
- Code class IP69K

(Cleaning with high-pressure cleaner possible) Solid pushing rod guide

 High positioning accuracy by directly coupled stroke measuring system

# Application

Linear actuators RA 60 K are used for electrically-operated proportioning tasks or as actuating element in applications with controloriented demands in short-time service. The range of application is versatile: The version for mobile applications was developed especially for the rough outdoor use and under corrosive environment influences.

# **Principal use**

- Agricultural and forest technology
- Mobile automotive engineering
- Conveyor and dosing technology
- Municipal technology

# **Fixing and installation**

The linear actuators RA 60 K have two fork eyes with  $\emptyset$  10 mm for the connection of user's constructions.

It has to be considered that the linear actuator has to be mounted protected against torsion. The pushing rod must be installed without any side loads. The connecting construction has to be designed so that no forced conditions act on the pushing rod.

The electric connection is made alternatively by the plug-type connector available as accessory or directly to a terminal strip in the control box by means of the cable wires.

#### Description

Linear actuators RA 60 K consist of a 12 VDC direct current drive, whose drive energy is transferred over a planetary gear and a spindle stroke actuator to the pushing rod.

The generated lifting force is available as push and pull force. The sturdy design with code class IP 69 k guarantees a trouble-free function also in rough operating conditions.

Linear actuators RA 60 K are maintenance free and can be operated with a duty cycle of up to 15 %.

The version with limit switches is equipped with 2 sensors, that prevent an unintentional movement to the mechanical stroke ends and thus the overload of the mechanics.

The end positions of the RA 60 K with stroke measuring system are definable by the signal of P the stroke measuring system.

# Operation

Linear actuators RA 60 K are supplied and operated with 12 V board supply of the vehicle electronics.

The version with stroke measuring system provides the absolute position values of the actuator to the control. Referencing is not required. RA 60 K can be integrated on request into existing bus systems and controlled by LIN or CAN bus.

Please contact us.





# Part no.: F2-XX-XX-1-C-XS3A

### **Technical data**

to 600 N
% of the push force
to 200 mm
, )
K

#### Operations

Control by external 12 V DC control

Optional control by BUS interface

# **Electrical interface**

Cable wires 0.34 mm<sup>2</sup> 12 VDC

**Mechanical interface** 

2 fork eyes Ø 10 mm

#### Accessories

Kit of plug-type connector

Bus control

# Material

Body:	polyamide, black,
	glass fibre reinforced
Guiding tube:	aluminium, anodized and
	powder coated
Pushing rod:	stainless steel

# Important notes!

The linear actuators RA60 K are resistant against corrosion, diesel, oil, detergents, fertilizers and salts.

The admissible environmental temperature is -20° up to +70.

Cleaning with high-pressure cleaner is admissible.

We recommend to install the cable ends or plug-type connectors protected against the environmental conditions to avoid penetration of humidity and premature corrosion.

# Version with limit switches

Current

tion

consump-

[A]

3.0

3.5

L + stroke

[mm]

367

467

567

**Duty cycle** 

[max. 1.5 min.]

max. 15 %

max. 15 %

Weight

[kg]

1.0

1.1

1.2

# Description

The version with limit switches has 2 integrated sensors, which automatically switch off the motor as soon as the upper or lower stroke end position is obtained.

This guarantees that the linear actuator does not mechanically push against the stop. The wires brown and white of this version are

to be connected to 12 V DC. By changing the polarity, switching over from retracting to extending is effected.

# **Current consumption**

As a function of the load the current consumption amounts lineraly up to 4.5 A at nominal load.

For a safe power supply, a supply current of at least 6 A is required.

**Technical data** 

Idle

running

[mm/s]

30

16

Speed

loaded

[mm/s]

20

9

L

[mm]

267

317

367

Force

[N]

300

600

Stroke

[mm]

100

150

200

Circuit diagram and configuration of cables for RA 60 K with stroke end disconnection

IP69K (exception: cable end)

#### Static retention force

200 N at lifting force 300 N 600 N at lifting force 600 N Since the actuators are designed without holding brake, the piston rod can be displaced in case of higher loads or vibrations and the actuator has to be readjusted, if necessary.

#### Important notes!

Code for part numbers

Maximum lifting force

Variant 24 V available on request.

F2-XX-XX-1-C-ES3A

Part no.

(push force)

**03** = 300 N

06 = 600 N

**10** = 100 mm

**15** = 150 mm

**20** = 200 mm

Stroke

The user has to provide a current limitation of 5.5 A.

In the case of a blockade, the control has to provide for a switching off of the power supply at the latest after 10 seconds to prevent an overload of the actuator.

For more information on technical data and tolerances, see operating manual or installation drawing.

Accessories

See page 3.

# Dimensions

16 ±0,5

white

brown

"+" (extend) "-" (retract)

"+" (extend) "-" (retract)

LF1

# 8.5 L $\pm 2$ $27 \pm 1$ $0 \times 10.2 \pm 0.1$ $0 \times 10.2 \pm 0.1$ $0 \times 10.2 \pm 0.1$ $34.5 \pm 1$ Cable wires isolated with wire bushs $0.34 \text{ mm}^2 \times 8 \log 0$ gastight square pressed



# Römheld GmbH

Subject to modifications

39 ±1

60 ±1

**१**∏≸

**A** 

2\_\_\_\_\_

# Description

The version with absolute stroke measuring See page 2. system is equipped with a linear potentiometer. A slider at the pushing rod produces a signal at the potentiometer, that is proportional to the position of the pushing rod. This signal can easily be evaluated by a priority control and is permanently available. Referencing is not required. Due to the direct connection of the absolute stroke measuring system to the pushing rod, one gets a precise stroke information with slight backlash.

With the stroke measuring system, controloriented applications and the compound of several linear actuators in synchronism can be realised.

Technical	data
Soo pogo (	)

Data stroke measuring system Connecting resistance 5 k Ω Linearity +1%

Connection according to the principle of a voltage divider to a stable reference supply point with max. 50 V.

#### Code for part numbers Part no. F2-XX-XX-1-C-AS3A

Maximum lifting force (push force) **03** = 300 N 06 = 600 N

# Stroke

**10** = 100 mm **15** = 150 mm **20** = 200 mm

# Circuit diagram and configuration of cables for RA 60 K with stroke measuring system



# Dimensions

See page 2.

# Important notes!

The stroke end positions must not be loaded mechanically. An approach in creep speed or switching off 2 mm before reaching the end positions is required.

# Accessories Kit of plug-type connector Superseal 5 Pol

Complete kit consisting of plugs and bushing with seals.

For crimping of the plug contacts, the user has to remove the wire bushs of the cable.

The bushing is suited for wire diameters of 0.75 mm<sup>2</sup> to 1.5 mm<sup>2</sup>.

# Part no. 3823-088



# Bus control

The optionally available bus board especially adapted to the customer's requirements offer beside the bus control further advantages such as

- Motor brake function
- Soft start
- Current limitation
- Excess-current release
- Limitation of duty cycle
- Function release blockade
- Error message